Model: HIT-2A-MIL

Hoffer Intelligent Rate Indicator & Totalizer

USER'S MANUAL



HP-326 November 2016



Perfecting Measurement™

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- 2. Model and serial number of the product under warranty, and
- 3. Repair instructions and/or specific problems relative to the product.

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Disclaimer

Specifications are subject to change without notice. Some pages are left intentionally blank.

CONTENTS

1.	Inti	oduction	- I
ľ	Model	Number Designation	- 2
2.	SPE	ECIFICATIONS	- 3
	2-1	General	_
2	2-2	Inputs	- 3
2	2-3	Battery Powered Version	- 4
2	2-4	DC Power/Loop Powered	- 4
2	2-5	AC Power	- 4
2	2-6	Analog (4-20mA) Output Option	- 4
2	2-7	Pulse Output Option	- 5
	2-8	Alarm Output Option	- 5
2	2-9	Physical	- 5
3.	The	ory of Operation	- 7
3	3-1	Functional Blocks	- 7
	3-1-		
	3-1-		- 7
	3-1-		
	3-1-		- 8
	3-1-		- 8
	3-1-		- 9
3	3-2	System Response Time	- 9
4.	Inst	allation	
	1-1	Typical Input Connections	11
	1-2	Typical Output Connections	14
4	1-3	Communications Connections	17
	1-4	Wiring	
۷	1-5	Terminal Designations	17
5.	Cor	figuration	
-	5-1	Local Configuration	
_	5-2	Default Configuration	
4	5-3	Remote Configuration	22
6.	Ope	eration and Maintenance	23
	5-1	Operation	
6	5-2	Maintenance	
6	5-3	Error Messages	
6	5-4	Analog Output Calibration	25

7.	Assembly/Disassembly Procedure	27
8.	Recommended Spare Parts List	29
Ap	pendix A – Default Configuration	30
Ap	pendix B - Communications	32
	Message Format And Timeout	
	Messages	

1. INTRODUCTION

The HIT-2A-MIL is a microprocessor-based flow rate indicator and totalizer. The instrument displays flowrate and a resettable total and is compatible with all Hoffer turbine flowmeters and the H.O.G. series positive displacement flowmeters.

The instrument can accept a low level frequency signal, a pulse signal, or a contact closure on the input and provides a linearized rate indication and total

The HIT-2A-MIL is fully configurable with K-factors, frequencies, and timebase being configured via the front panel key switches or the RS232 communications port. The configuration and monitoring can be performed using any PC based communications program (e.g., HyperTerminal) or ASCII terminal.

The instrument is housed in an attractive NEMA 4X polycarbonate enclosure and can be mounted directly on a flowmeter or wall mounted using an optional mounting brackets or an EX enclosure.

This instrument has been designed to conform to the EMC-Directive of the Council of European Communities 89/336/EEC and the following standards:

Generic Emission Standard EN 61000-6-3 Residential, Commercial & Light Industry Environment.

Generic Immunity Standard EN 61000-6-1 Residential, Commercial & Light Industry Environment.

Electrostatic discharge requirements EN 61000-4-2

Radiated, radio-frequency, electromagnetic immunity EN 61000-4-3

Electrical fast transient/burst requirements EN 61000-4-4

Immunity to conducted disturbances EN 61000-4-6

Model Number Designation

MODEL HIT-2A-MIL TOTALIZER/FLOW RATE INDICATOR

MODEL HIT-2A-(_/	<u>\</u>)-(_E	3_)-(_0	<u>_)-(_</u>	<u>_)-(</u> _	<u>_</u>)- N	ΛIL
ENCLOSURE STYLE					-	
INPUT POWER						
LOOP POWERED ANALOG OUTPUT		•				
OPTIONS						
MOUNTING				·		
SPECIAL FEATURE						

ENCLOSURE STYLE

MODEL HIT-2A-(A)-()-()-()-()-()-MIL

OPTION (A)

- (2) NEMA 4X ENCLOSURE, HIT-2A-MIL MOUNTED BEHIND CLEAR COVER.
- (3) EXPLOSION-PROOF ENCLOSURE.
- (3A) ATEX Exd ENCLOSURE, STANDARD BLUE
- (3B) ENCLOSURE FOR BRAZIL, GRAY
- (P) PANEL MOUNT SURFACE MOUNTED ON CUSTOMER'S PANEL; NO ENCLOSURE BEHIND PANEL ON HIT-2A-MIL.
- (PD) PANEL MOUNT ENCLOSURE WITH CLEAR DOOR AND LOCK
- (4) NEMA 1 ENCLOSURE (HIT-2A-MIL MOUNTED TO THE OUTSIDE OF CLEAR COVER FOR INDOOR/DRY INSTALLATION ONLY)
- (5) NEMA 4X ENCLOSURE/HIT2A ENCLOSURE (MOUNTED BEHIND CLEAR COVER WITH SUNSHADE.)

INPUT POWER

MODEL HIT-2A-()-(B)-()-()-()-MIL

OPTION (B)

- (A) INTERNAL BATTERIES (TWO EACH).
 THIS OPTION CAN NOT SUPPORT REDI-PULSE COILS.
- (B) 8 TO 30 VDC EXTERNAL POWER.
- (AC) UNIVERSAL 100-240 VAC @ 0.15A 50/60 HZ.
- (X) ENTER (X) IF LOOP POWERED ANALOG OUTPUT OPTION (C) OR (D) BELOW IS SELECTED.

LOOP POWERED ANALOG OUTPUT MODEL HIT-2A-(__)-(__)-(__)-(__)- MIL

OPTION (C)

- (C) LOOP POWERED 4-20MA OUTPUT (8 TO 30 VDC)
- (D) LOOP POWERED 4-20MA OUTPUT WITH INTERNAL BATTERIES

OPTIONS

MODEL HIT-2A-(__)-(__)-(__)-(__)- MIL

OPTION (□)

- (L) 20 POINT LINEARIZATION.
- (RR) REMOTE RESET
- (AL) LOW ALARM* OPTO ISOLATED OPEN COLLECTOR.
 (AH) HIGH ALARM* OPTO ISOLATED OPEN COLLECTOR.
- (AH) HIGH ALARM* OPTO ISOLATED OPEN COLLECTOR (HT) HEATER; REQUIRES DC POWER INPUT OPTION.
- *NOTE: EITHER LOW OR HIGH ALARM IS AVAILABLE, NOT BOTH.

MOUNTING

MODEL HIT-2A-(__)-(__)-(__)-(__)-(__E)- MIL

OPTION (E)

- (F) NEMA 4X STYLE 2 ENCLOSURE MOUNTED ON TURBINE.
 MUST BE USED WITH "X" RISER TURBINE OPTION.
- (FHT) 8" LONG TEMPERATURE RISER FOR NEMA 4X STYLE 2
 ENCLOSURE MOUNTED ON TURBINE. REQUIRED WHEN
 FLUID TEMPERATURES EXCEED 140 DEG. F. USED WITH
 "X" RISER TURBINE OPTION.
- (FX) EXPLOSION-PROOF STYLE 3 ENCLOSURES MOUNTED ON TURBINE. MUST BE USED WITH "X" RISER TURBINE OPTION.
- (FXHT) 8" LONG TEMPERATURE RISER FOR EXPLOSION-PROOF STYLE 3 ENCLOSURES MOUNTED ON TURBINE. REQUIRED WHEN TEMPERATURES EXCEEDS 140 DEG. F. USED WITH "X" RISER TURBINE OPTION.
- (NP) ENCLOSURE PIPE MOUNTING KIT, 2" PIPE OR SMALLER. SPECIFY IF PIPE IS VERTICAL OR HORIZINTAL.

SPECIAL FEATURES

MODEL HIT-2A-(__)-(__)-(__)-(__)- MIL

\underline{OPTION} (F)

- (MIL) MIL-S-901D, "SHOCK TESTS, H.I. (HIGH IMPACT) SHIPBOARD MACHINERY, EQUIPMENT, AND SYSTEMS, REQUIREMENTS FOR;" DATED 17 MARCH 1989. MIL-STD-167-1, MECHANICAL VIBRATION OF SHIPBOARD EQUIPMENT (TYPE I ENVIRONMENTAL & TYPE II INTERNALLY EXCITED), 1 MAY 1974.
- (X) NO SPECIAL FEATURES
- NOTES: 1. OPTO-ISOLATED OPEN COLLECTOR TRANSISTOR IS STANDARD WITH ALL UNITS.
 - 2. A LOCAL RESET MAGNET IS STANDARD WITH ALL UNITS EXCEPT IF REMOTE RESETOPTION IS SELECTED.
 - 3. WINDOWS® BASED SETUP DISC AND, IF REQUIRED, 6 FT COMMUNICATION CABLE. IF THREE OR MORE UNITS ARE ORDERED ON THE SAME PURCHASE ORDER ONE SET IS SUPPLIED AT NO CHARGE.

SPARE BATTERIES:

MODEL ER26500M OR EQUIVALENT; LITHIUM SIZE C, 3.6V 6000 mAh (TWO BATTERIES ARE REQUIRED FOR BATTERY POWERED UNITS. ONE BATTERY IS REQUIRED FOR ALL OTHER POWER OPTIONS TO RETAIN TOTAL DISPLAY IF POWER FAILS.

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2. SPECIFICATIONS

2-1 General

Display: LCD, continuously powered

Total: 8 digits 0.26" high. Resettable from front

panel.

Total Units: GAL, LIT, FT3, M3, BBL, & "blank".

Rate: 5 digits 0.5" high. Rate Units: /MIN, /HR, & /DAY

K-factor: The pulses per unit of Total (e.g.

pulses/gallon) are configurable in the range

0.001 to 99,999,999.

Linearization: Up to 20 points.

Decimal Points: Decimal Point positions are fully

configurable for both rate and total.

Accuracy: ± 1 count Temperature drift: $50 \text{ ppm/}^{\circ}\text{C}$

2-2 Inputs

Magnetic Pickup:

Frequency Range: 0.2 Hz to 5000 Hz.

Signal Type: Low-level sinusoidal (30 mV P-P minimum).

Opto-Isolated DC Pulse:

Frequency Range: 0 Hz to 3000 Hz.

Signal Type: DC pulse.

High (Logic 1): 4 to 30 VDC Low (Logic 0): <1 VDC Min Current: 0.5 mA Hystersis: 0.4 VDC

Min Pulse width: 0.1 msec

Contact Closure:

Frequency Range: 0 Hz to 5000 Hz

Signal Type: Contact closure to DC common

High (Logic 1): Open or 4 to 30 VDC

Low (Logic 0): < 0.5 VDC

Internal Pull-up: $220 \text{ k}\Omega \text{ to } +3.3 \text{ VDC}$

Reset:

Signal Type: Contact closure to DC common

High (Logic 1): 4 to 30 VDC Low (Logic 0): < 0.5 VDC Min Current: 0.5 mA Min On: 25 msec

Internal Pull-up: $100 \text{ k}\Omega \text{ to } +3.3 \text{ VDC}$

External Magnet: Activates internal reed switch

2-3 Battery Powered Version

Type: Two C-size lithium battery packs.

Battery Life: 4 years typical*

10 years typical* for external power.

* With the pulse output OFF. With pulse output ON 30% less.

2-4 DC Power/Loop Powered

Voltage: 8 to 30 VDC Current: 4 mA

Loop Burden: 8 VDC maximum

Supply Backup: One (1) C-size Lithium battery Protection: Reverse polarity protected

2-5 AC Power

Voltage: 100 to 240 VAC Frequency: 47 - 440 Hz Current: 150 mA Line Regulation: $\pm 0.3\%$, typ

Protection: Short circuit, Over voltage, & Over

temperature

Supply Backup: One (1) C-size Lithium battery

2-6 Analog (4-20mA) Output Option

Scale: 4 - 20 mA follows rate. Accuracy: 0.02% of Full Scale @ 20°C.

Temperature drift: 40 ppm/°C Update Time: 2.0 seconds. Connection: Two wire.

Protection: Reverse polarity protected

2-7 Pulse Output Option

Type: Opto-isolated open collector (100 VDC,

100 mA).

Divider: 1, 10, 100, or OFF

Rate & Duration: See below.

SPEED (Hz) 1 2 4 8 Min on/off (msec) 500 250 125 62.5

2-8 Alarm Output Option

Type: Opto-isolated open collector (100 VDC,

100 mA).

Function: Rate or Total

2-9 Physical

Temperature: Operating: -40°F (-40°C) to 158 °F (70°C)

-58°F (-50°C) with optional

heater.

32°F (0°C) to 140 °F (60°C) with AC power option.

Humidity: 0 – 90% Non-condensing.

Packaging: Wall Mount & Explosion proof

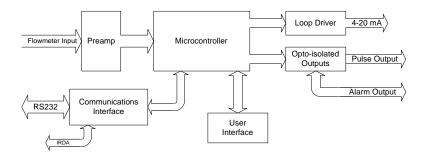
Dimensions for Wall 4.33" (110 mm) wide x 4.33" (110 mm) long

Mount enclosure: 4.33" (110 mm) tall.

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3. THEORY OF OPERATION

The HIT-2A-MIL consists of six functional blocks. These functional blocks are the User Interface, Preamplifier, Microcontroller, Loop Driver, Pulse and Alarm Output, and Communications Interface.



3-1 Functional Blocks

3-1-1 User Interface

The User Interface consists of a custom LCD display with 4 push buttons; OK, P, > (right arrow), and ^ (up arrow) and an optional external reset. Using the buttons and the displayed information, the user can enter setup parameters (rate units, pulses per unit of flow, etc.) as well as setup information for the pulse output and 4-20mA output. The optional external reset maybe used to reset the accumulated total to zero and clear the displayed accumulated total.

3-1-2 Preamplifier

The Preamplifier accepts the input from the flowmeter. The Preamplifier applies amplification, low-pass filtering, and wave-shaping to the input signal. The wave shaping function converts the signal into a square-wave before sending it to the Microcontroller

3-1-3 Microcontroller

The Microcontroller accepts the square-wave output of the preamplifier and performs all of the calculations that are required to control the Loop Driver. After measuring the frequency of the

square-wave, the Microcontroller uses the following equations to compute the flow rate and current.

$$flowrate = \frac{frequency}{Kfactor} x60^{FM} xCF$$

Where:

Kfactor = Is dependent on the Flow Calculation Method setting and is either the Average K-Factor or the Linearized

K-Factor from the Frequency / K-Factor table.

FM = Is the Flow rate Units setting of 0, 1, 2 or 3. Where "0" is for Seconds, "1" is for Minutes, "2" is for Hours and "3" is for days.

CF = Is the Correction Factor setting.

$$current = 4mA + \left(16mAx \frac{flowrate}{AF}\right)$$

Where:

AF = is the 20 mA maximum Flow Rate value.

If the calculated flowrate is greater than the AF setting, the current will be set to 24mA to signal an "Over-range" condition. After calculating the current, the Microcontroller digitally sends the current information to the Loop Driver.

3-1-4 Loop Driver

The loop driver uses the digital information received from the Microcontroller to set the current of the loop. The Loop Driver supplies power to both the Preamplifier and Microcontroller.

3-1-5 Pulse and Alarm Output

The Pulse and Alarm outputs are two optically isolated open collector outputs. The alarm output activates when the total flow or the rate reaches a user defined level. The pulse output activates to give a scaled pulse output indicative of the total flow. Both of these outputs are rated for 100 VDC at 100 mA.

3-1-6 Communications Interface

The communication is provided through a RS232C interface to the Microcontroller. The external terminal device provides the power for the RS232 interface. The Communications Interface is used to configure and trouble-shoot the device.

3-1-7 Clearing Total

The Total amount stored in HIT-2A-MIL memory can be cleared from the front panel program menu, by external momentary switch wired to the reset input, or by external magnet. The magnet has to be brought close to top of the front panel.

3-2 System Response Time

The displayed Rate and Total are updated every two (2) seconds. The analog output response time to reach steady state due to a change in the flow rate is also approximately two (2) seconds. When flow stops, the time for the analog output to return to 4 mA will be between 3 and 12 seconds, depending on the Maximum Sample Time (MST) setting. MST is adjusted using the NB= (DATA) command, where NB is a value between 1 and 80. The default MST setting is NB= 1. Adjusting the MST is only recommended for low flow applications where the minimum input frequency is below 1 Hz.

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4. INSTALLATION

The HIT-2A-MIL has an input conditioning circuit, which accepts signals from most frequency or pulse producing flowmeters.

The input will interface directly to:

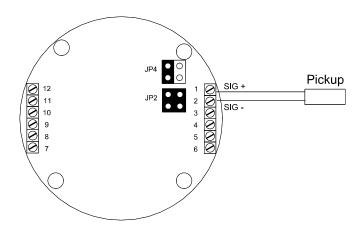
- Turbine Flowmeters
- Reed Switches
- Logic Signals
- Open Collector Outputs

The input is protected for over voltage up to 50 volts.

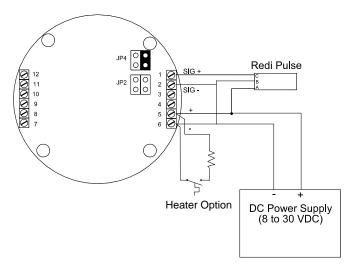
The flowmeter input (terminals 1 & 2) must be configured for the selected signal type by appropriately setting the input selection jumpers found on the HIT-2A-MIL signal input board (see following for jumper positions).

4-1 Typical Input Connections

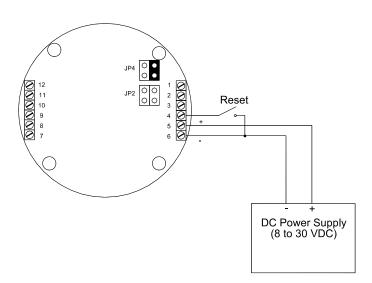
MAG Coil & Reed Switch Pickups



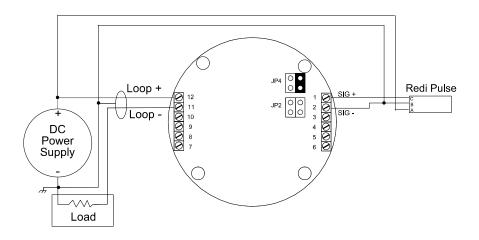
TTL Redi-Pulse Pick-up with DC Power



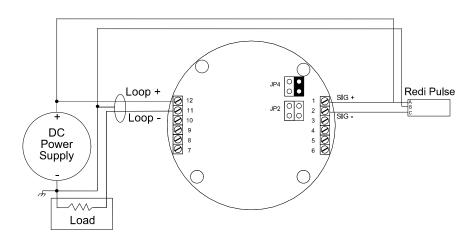
Reset Input



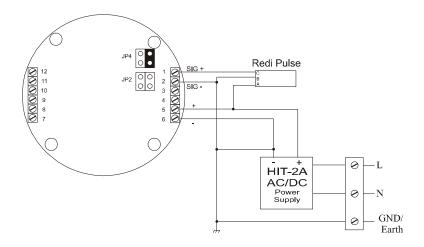
Loop Power with TTL Redi-Pulse



Loop Power with Redi-Pulse Open Collector Output

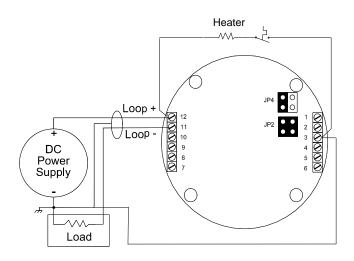


TTL Redi-Pulse with AC Power

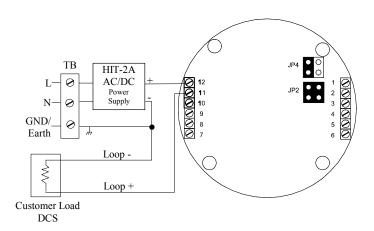


4-2 Typical Output Connections

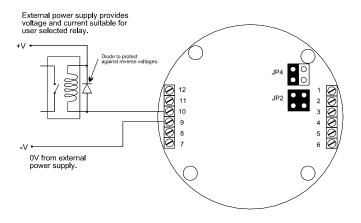
Analog Output with DC Power



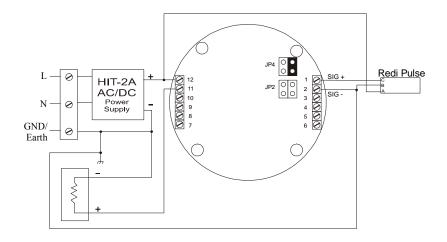
Analog Output with AC Power



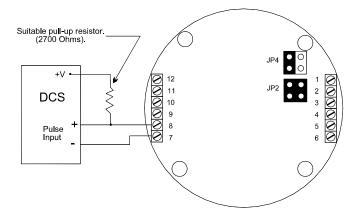
Alarm Output



Analog Output and TTL Redi-pulse with AC Power



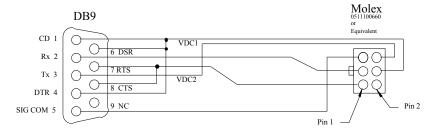
Pulse Output



4-3 Communications Connections

Communications with the HIT-2A-MIL using a terminal or a PC using the Windows configuration program requires the use of the HOFFER HIT2A-301 Communications Cable. The communication circuits of the HIT-2A-MIL are externally powered and the power for these circuits is supplied by the RS232 serial port of the computer/terminal. The serial port configuration must be set to the following:

Baud rate: 2400
Data bits: 8
Parity: none
Stop bits: 1
Handshaking: None



Hoffer HIT2A-301 Communications Cable

4-4 Wiring

When connecting the HIT-2A-MIL, it is good practice to use shielded cable. The shield should be connected to earth ground near the instrument. The other end of the shield should not be connected.

In order to comply with the requirements for Electromagnetic Compatibility, as per EMC-Directive 89/336/EEC of the Council of European Community, this wiring practice is mandatory.

4-5 Terminal Designations

<u>Terminal</u>	Description
1	Signal/Pulse Input (+)
2	Signal/Pulse Input (-)
3	Shield
2 3 4 5 6	Reset Input
5	VDC (+)
6	VDC (-) / Reset Common
7	Pulse out (-)
8	Pulse out (+)
8 9	Alarm (-)
10	Alarm (+)
11	4-20 mA (-)
12	4-20 mA (+)

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5. CONFIGURATION

The HIT-2A-MIL is fully configurable, with all parameters being stored in non-volatile memory.

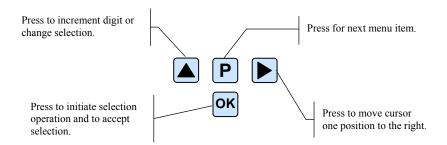
The instrument may be configured using the front panel keys, a PC running Terminal Emulation software, a ASCII terminal, or a PC running the HIT-2A-MIL Configuration software.

5-1 Local Configuration

Local configuration is accomplished using the four buttons below the display while viewing the configuration parameters on the display.

The local configuration mode is entered by pressing the | P | button

Once in the local configuration mode each of the four buttons have a special purpose as detailed below.



Display	Option	Menu item Description	
CLERreat		Clear Total	
no	Yes No	Clears accumulated total and sets TOTAL display to zero.	
10000000		Tag Number	
ŁRS		User defined 5-digit number.	
ค บ&-ค9&	Linear	Linearization Method	
FRC NN	Average	Sets the flow calculation method to average K-factor or K-factor table.	
888888		K-factor Decimal Point	
F80 8		Set K-factor decimal point location.	
1,000		Average K-factor	
ጸ የ ጸር		Enter average K-factor.	
PointS	2	Number of Points	
S 0	to 20	Sets the number of entries in the linearization table.	
4 999,98:	0	Frequency 1-20	
Fr 0:	to 5000	Enter a frequency in Hz for each entry in the table. Decimal point is fixed.	
1.000		K-factor 1-20	
FACO:		Enter a k-factor in pulses/gal for each entry in the table.	
1,000	0.001	Correction Factor	
C FRC	to 99999.999	User defined number between 0.001 and 99999.999 to multiply flow and total. Default 1.0.	
	100 = GAL	Total Units	
tot unit	110 = FT3	Select Total units.	
:88	140 = LIT 150 = M3 180 = BBL	If custom is selected all indicators are off. (gal, lit, ft3, m3, bbl, custom)	
0,000000.0		Total Decimal Point	
tot d		Set Total decimal point location.	

Display	Option	Menu item	
	SEC	Description	
۶۴۰ ن	Min	Rate Units	
88 iv	HrS dAY	Select RATE units.	
00000,000		Rate Decimal Point location	
દ ક		Set Rate decimal point location.	
ડક્ષ્ટાદ	1	Max Sample Time	
•	to 80	Set maximum time in seconds to sample the input frequency. Default 1.	
1,000		Out Low	
outio		Sets flow rate value for 4 mA output.	
99,999		Out High	
outXi		Sets flow rate value for 20 mA output.	
0 .cc c	oFF	Pulse Scale	
PULSE S	1 10	Sets scale for pulse out. 1, 10, 100	
off	100	units of total for one pulse out. OFF- turns pulse out off.	
PULSE F	1 2	Pulse Frequency	
8	4 8	Sets frequency of burst of pulse out. (1, 2, 4, 8)	
PRSS	0000	Password	
1534	to 9999	Sets 4-digit password. Default 0000.	
unit LoE	Yes	Lock Unit	
00	No	Locks the unit.	
818-00	oFF	Alarm Function	
	rAtE	Select Rate or Total for alarm	
off	tot	output. OFF- turns alarm function off.	
188888.8		Alarm Out	
868-0		Sets value to activate the alarm output. Default 99999.999	

Display	Option	Menu item Description	
0,0 58 8 &		Sets Total Sets Total to user defined value.	
Cur out r8tE	rAtE 4 12 20	Current Out Sets analog output to follow rate or predefined level.	
Pul EESE	Yes No	Pulse Output Test Outputs a test frequency of 1Hz, 50% duty cycle.	
AL EESE	Yes No	Alarm Output Test Activates alarm output.	

5-2 Default Configuration

The HIT-2A-MIL is configured by the factory before shipment. When the instrument is purchased with a Hoffer Flowmeter or when calibration and configuration data are supplied, the instrument is configured as specified. When the instrument is shipped without specific configuration information, the instrument is configured with default values. Refer to Appendix A for a listing of the HIT-2A-MIL factory default configuration.

5-3 Remote Configuration

The HIT-2A-MIL may be configured remotely via the RS232 communications interface. Refer to Appendix B for the communications details

6. OPERATION AND MAINTENANCE

6-1 Operation

A suitable pulse producing device or flow meter is wired to the HIT-2A-MIL Signal Input terminals 1 (Sig +) and 2 (Sig -). The Signal Input circuit must be configured for the connected input device using the appropriate jumper blocks.

Internal batteries, external DC, or a loop current may provide power to the unit. For all power options other than internal batteries (A), if the primary power is lost, the internal backup battery will provide for continued operation of the totalizer.

Once properly wired, the operation of the HIT-2A-MIL is automatic.

The flow totalizer is updated every 2 seconds* with the latest total. If no input counts are received the unit remains in a low power state to conserve power.

The flow total may be cleared by the front panel switch sequence or by a contact closure on the remote reset terminal to circuit common.

To reset the unit from the front panel, the following key sequence is required:

Press P CLEArtot is displayed
Press OK To enter edit mode.
Press ▲ To select yes
Press OK To clear total
Press ▲ To return to operating mode

The flow rate indicator measures the flow rate once every 2 seconds* and display the flow rate.

If the input pulses are not detected within the maximum sample time (1 to 80 seconds), a flow rate of zero (0.00) is indicated.

The analog output is scaled based on the user selected zero and full scale and the measured flow rate.

The pulse output generates a burst of pulses every 2 seconds* in accordance with the instrument setup of pulse scaling.

^{*} A large sample time setting and internal math operations may delay the update rate.

6-2 Maintenance

The only scheduled maintenance for the HIT-2A-MIL is periodic battery replacement.

The instrument has a battery monitor feature which illuminates when the lithium battery voltage approaches its end of life. A descriptor, "LO BAT", illuminates when the battery voltage falls below this predetermined value. The low battery detector operates correctly with all power options.

The battery, or batteries, should be replaced within several weeks of the first occurrence of low battery warning. Left unattended, the unit may become inaccurate, cease to operate, lose setup information, or malfunction.

The batteries should be replaced one at a time to avoid interrupting the power.

6-3 Error Messages

The HIT-2A-MIL is provided with extensive self checking which is used in reporting malfunctions or unusual operating conditions. When an error occurs, the display will flash with an error message until the user presses the OK button acknowledging the error condition. Once an error condition is acknowledged, the error message will not be displayed again for 60 seconds if the cause of the error is still present.

If the alarm output is active from an alarm caused by a rate or total condition, depressing the \mathbf{OK} button while the display is showing the rate and total will reset the alarm output if the condition that caused the alarm is no longer present. If the alarm output is active because of a test command, depressing the \mathbf{OK} button will not reset the alarm output.

The following table illustrates the Error Messages, the problem or cause, and a recommended corrective action:

ERROR MESSAGE	CAUSE	CORRECTIVE ACTION
EFOFUE	Total rollover.	None
EPULSE	Pulse out overflow.	Use different pulse scaler or lower totalizer decimal point
EE-ES	EEPROM reset to factory defaults.	Consult factory
E-REE	Flow rate exceeds the flow rate display capability.	Reduce flow rate or use lower flow rate decimal point
EFL.	Flow rate exceeds the 20 mA flow rate setting.	Reduce flow rate or increase 20 mA flow rate setting
LO BRY	Low battery.	Replace battery(ies)

6-4 Analog Output Calibration

The 4-20 mA analog output has been accurately set to 20.000 mA by the factory. No adjustment is required.

The 4-20 mA output may be verified periodically by installing a digital milliamp meter in series with the analog output and simulating a full scale or over range flow rate.

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7. ASSEMBLY/DISASSEMBLY **PROCEDURE**

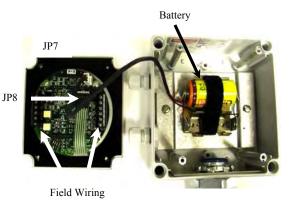
Follow the disassembly instruction below for accessing electronic terminal block, replacing the battery, or replacing the electronic PCB assembly.

Remove four screws with a Phillips head screwdriver and lift off the cover.



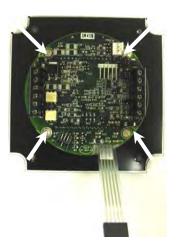
After the cover is removed, use a flathead screwdriver to remove four screws and washers from the panel.





Disconnect JP7 connector by pulling up. Disconnect JP8 by pulling outwards.

Remove four screws with a Flat-head screw driver. Two of the screws have washers and internal teeth washers. Finally, remove the PC board.



To re-assemble the unit, follow the instruction above in the reverse order.

8. RECOMMENDED SPARE PARTS LIST

The following table lists the recommended spare parts.

Hoffer Model/ Stock Numbers	Description
PCA170 800-0149	Electronic PCB assembly
100-2477	C-size battery

APPENDIX A – DEFAULT CONFIGURATION

Factory default configuration:

FIELD	Value
CL	No
DN	10000000
FC	0 (Average)
KD	3
AK	1.00
NP	20
F01	4999.981
F02	4999.982
F03	4999.983
F04	4999.984
F05	4999.985
F06	4999.986
F07	4999.987
F08	4999.988
F09	4999.989
F10	4999.990
F11	4999.991
F12	4999.992
F13	4999.993
F14	4999.994
F15	4999.995
F16	4999.996
F17	4999.997
F18	4999.998
F19	4999.999
F20	5000.000
K01	1.00
K02	1.00
K03	1.00
K04	1.00
K05	1.00
K06	1.00
K07	1.00
K08	1.00
K09	1.00
K10	1.00
K11	1.00
K12	1.00
K13	1.00
K14	1.00

EIELD	17.1
FIELD	Value
K15	1.00
K16	1.00
K17	1.00
K18	1.00
K19	1.00
K20	1.00
CF	1.000
TU	100 (GAL)
TD	1
FM	1 (MIN)
RD	3
NB	01
LF	000.000
AF	99.999
PS	0 (OFF)
FO	8
PA	1234
LK	No
UA	Off
AL	99999.981
ST	000.000
OC	0 (Rate)
TP	No
AS	No

APPENDIX B - COMMUNICATIONS

Message Format And Timeout

Communication messages consist of a string of ASCII characters terminated by a carriage return character. The maximum message length coming to the HIT-2A-MIL is 20 characters, including the carriage return. The HIT-2A-MIL will transmit no more than 35 characters before transmitting a carriage return.

If a message longer than A 20 characters command is sent, the instrument responds with

```
"Command Sequence is Too Long!<NL>"
```

If an unrecognized or invalid command is sent, the instrument responds with

```
"Invalid Command! <NL>"
```

The sending unit RS232C serial port configuration must be configured as follows:

Baud rate: 2400
Data bits: 8
Parity: none
Stop bits: 1
Handshaking: none

The HIT-2A-MIL echoes all received messages and then transmits a response string terminated with a carriage return. If the sending unit takes longer than one minute to send a message, the HIT-2A-MIL aborts the message by clearing the receive buffer.

If the sending unit (PC or other such device) wishes to change a setting on the HIT-2A-MIL, the sending unit shall follow the command with an equal sign ("=") with the data following immediately after the equal sign. The carriage return terminates the message.

Any HIT-2A-MIL response that sends data back to the sending unit shall have an equal sign ("=") followed by the data. Space is allowed between the equal sign and the data on the return message, but the total message length is limited to 35 characters.

READ Example:

If the sending unit wishes to read the number of points that the HIT-2A-MIL has in the K factor table, the sending unit shall send

The HIT-2A-MIL echoes the sent message, and responds with

"NUM PTS =
$$2 < CR > "$$

WRITE Example:

If the sending unit wishes to change the number of points to 20 in the K factor table, the sending unit shall send

The HIT-2A-MIL echoes the sent message and responds with

"NUM PTS =
$$20 < CR > "$$
.

The HIT-2A-MIL checks the ranges for data and rejects writes that are not within the allowed range. If the sending unit sends data that is not within the allowed range, the HIT-2A-MIL echoes the sent message and responds with the value that is currently stored in the HIT-2A-MIL.

Example:

If the sending unit wishes to change the max sample time to 2000 from the previous setting of 10, the sending unit shall send

The HIT-2A-MIL echoes the sent message, and responds with

"MAX M TIME=
$$10 < CR > "$$
.

Messages

Commands Supported By Communications Messages

Command	Description/Allowed Data/Response
\mathbf{CL}^1	Clear Total "0" to "99999999"
	"TOTAL = 0"
DN	Tag Number "0" to "99999999"
	"TAG NUM = (DATA)"
	The first three digits are the units code for total. Changing these digits will change the TU settings.
FC	Linearization "0" = Average K factor "1" = Linearization table
	<pre>"F C METHOD = AVG" for Average K factor or "F C METHOD = LIN" for Linearization table</pre>
KD	K Factor Decimal Point Location "0" for 00000000. "1" for 0000000.0 and all K Factors are less than 9999999.9, otherwise not allowed "2" for 000000.00and all K Factors are less than 999999.99, otherwise not allowed "3" for 00000.000 and all K Factors are less than 99999.999, otherwise not allowed
	"K-FAC DECL=(DATA)"
AK	Average K Factor "0.001" to "99999.99" if KD = 3 "9999999.9" if KD = 2 "9999999.9" if KD = 1 " 99999999" if KD = 0
	"AVG KFAC =(DATA)"

F## Fre	"NUM PTS = (DATA)" requency 1-20 F01 has a range of "0.000" to the value of F02 minus 0.001; F20 has a range of the value from F19 plus 0.001 to "5000.000"; Frequencies F02 to F19 must be 0.001 greater than the previous frequency and 0.001 less than the next frequency. "FREQ ## = (DATA)" for F01 through F20. Data to fixed three decimal places. -Factor 1-20 "K-FACT # = (DATA)" for K01 through K09. "K-FACT ## = (DATA)" for K10 through K20. DATA to decimal places as per KD command. orrection Factor "0.001" to "9999999.999" "CORR FACT = (DATA)"
K## K	"NUM PTS = (DATA)" requency 1-20 F01 has a range of "0.000" to the value of F02 minus 0.001; F20 has a range of the value from F19 plus 0.001 to "5000.000"; Frequencies F02 to F19 must be 0.001 greater than the previous frequency and 0.001 less than the next frequency. "FREQ ## = (DATA)" for F01 through F20. Data to fixed three decimal places. -Factor 1-20 "K-FACT # = (DATA)" for K01 through K09. "K-FACT ## = (DATA)" for K10 through K20. DATA to decimal places as per KD command. orrection Factor "0.001" to "9999999.999"
K## K	requency 1-20 F01 has a range of "0.000" to the value of F02 minus 0.001; F20 has a range of the value from F19 plus 0.001 to "5000.000"; Frequencies F02 to F19 must be 0.001 greater than the previous frequency and 0.001 less than the next frequency. "FREQ ## = (DATA)" for F01 through F20. Data to fixed three decimal places. Factor 1-20 "K-FACT # = (DATA)" for K01 through K09. "K-FACT ## = (DATA)" for K10 through K20. DATA to decimal places as per KD command. Determinent of the previous frequency and 0.001" to "99999999.999"
K## K	F01 has a range of "0.000" to the value of F02 minus 0.001; F20 has a range of the value from F19 plus 0.001 to "5000.000"; Frequencies F02 to F19 must be 0.001 greater than the previous frequency and 0.001 less than the next frequency. "FREQ ## = (DATA)" for F01 through F20. Data to fixed three decimal places. Factor 1-20 "K-FACT # = (DATA)" for K01 through K09. "K-FACT ## = (DATA)" for K10 through K20. DATA to decimal places as per KD command. Direction Factor "0.001" to "9999999.999"
CF Co	fixed three decimal places. -Factor 1-20 "K-FACT # = (DATA)" for K01 through K09. "K-FACT ## = (DATA)" for K10 through K20. DATA to decimal places as per KD command. orrection Factor "0.001" to "9999999.999"
CF Co	"K-FACT # = (DATA)" for K01 through K09. "K-FACT ## = (DATA)" for K10 through K20. DATA to decimal places as per KD command. prrection Factor "0.001" to "9999999.999"
	"0.001" to "9999999.999"
TU To	
	"100" for gallons "140" for liters "110" for cubic feet "150" for cubic meters "180" for barrels All other integer values from 0 and less than 999 will map to custom units
	"TOT UNITS = (DATA)" (DATA) shall be: "GAL" for gallons "LIT" for liters "FT3" for cubic feet "M3" for cubic meters "BBL" for barrels "CUS" for custom

Command	Description/Allowed Data/Response
TD	Total Decimal Point Location "0" for 00000000. "1" for 0000000.0. If UA set to Total and AL is greater than 9999999.9 it not allowed. "2" for 000000.00. If UA set to Total and AL is greater than 999999.99 it not allowed. "3" for 00000.000. If UA set to Total and AL is greater than 99999.999 it not allowed.
FM	"FLOW DEC L=(DATA)" Rate Units "0" for seconds "1" for minutes "2" for hours "3" for days
	"FLOW UNITS=(DATA)" (DATA) shall be: "SEC" for seconds "MIN" for minutes "HR" for hours "DAY" for days
RD	Rate Decimal Point Location "0" for 00000. "1" for 000000.0 and AF (and AL if UA set to Rate) is less than 9999999.9, otherwise not allowed. "2" for 000000.00 and AF (and AL if UA set to Rate) is less than 999999.99, otherwise not allowed. "3" for 00000.000 and AF (and AL if UA set to Rate) is less than 99999.999, otherwise not allowed.
NB	"MAX M TIME=(DATA)"
LF	Out Low "0.000" to a maximum value of the Out High setting "4mA FLOW = (DATA)"

Command	Description/Allowed Data/Response
AF	Out High Minimum is the Out Low Setting (LF) to a maximum of the following: "99999.99" if RD = 3 "9999999.9" if RD = 2 "9999999.9" if RD = 1 "99999999" if RD = 0
PS	"20mA FLOW = (DATA)" Pulse Scale "0" for OFF "1" for 1 "10" for 10 "100" for 100
	"PULS SCALE=(DATA)" (DATA) shall be: "OFF" for OFF "1" for 1 "10" for 10 "100" for 100
FO	Pulse Frequency "1" "2" "4" "8" "PULS FREQ = (DATA)"
PA	Password "0" to "9999" "PASS WORD = (DATA)"
LK	Lock Unit "0" for NO "1" for YES
	"LOCK UNIT = (DATA)" (DATA) shall be: "YES" for YES "NO" for NO

Description/Allowed Data/Response
Alarm Function
"0" for OFF
"1" for RATE
"2" for TOTAL
"ALARM FUNC=(DATA)"
(DATA) shall be:
"OFF" for OFF
"RAT" for RATE
"TOT" for TOTAL
Alarm Out
"0.001" to a maximum defined as follows:
If UA is RATE:
"99999.999" if RD = 3
"999999.99" if RD = 2
"9999999.9" if RD = 1
" 99999999" if RD = 0
If UA is Total or Off:
"99999.999" if TD = 3
"999999.99" if TD = 2
"9999999.9" if TD = 1
" 99999999" if TD = 0
"ALARM OUT =(DATA)"
Set Total
"0.000" to a maximum defined as follows:
"99999.999" if TD = 3
"999999.99" if TD = 2
"9999999.9" if TD = 1
" 99999999" if TD = 0
"TOTAL = (DATA)"
(DATA) = "0" to the following maximums:
"99999.999" if $TD = 3$
"999999.99" if TD = 2
"9999999.9" if TD = 1
" 9999999" if TD = 0

Command	Description/Allowed Data/Response
ос	Current Out "0" - Current output follows rate. "1" - Current output set to 4mA. "2" - Current output set to 12mA. "3" - Current output set to 20mA. For "0", response = " Output equal to input." For "1", response = " Output is 4mA." For "2", response = " Output is 12mA." For "3", response = " Output is 20mA."
PR	Pulse Output Controlled By PS and FO " Pulse Output Released " The PS and FO menus shall control the pulse output. Used to terminate the TP command.
TP	Output 1Hz Test Frequency for Pulse Output " Test Pulse Output " Sets output to 1Hz, 50% duty cycle signal. This mode is for factory test.
RA	Release Alarm Output for Control According to Menu Settings " Alarm Released " Releases alarm output for control by the alarm output settings.
AS	Alarm Output Test "0" - Alarm output is set low. "1" - Alarm output is set high. For "0", response = " Alarm Active " For "1", response = " Alarm Released " After using the "AS" command, you must initiate a RA command to allow HIT-2A-MIL to return to normal operation.

System Commands Supported by Communications Messages

System Command	Description/Response/Comments
OI	Output 4mA " Output is 4mA."
	Current output set to 4mA.
МО	Output 12mA " Output is 12mA."
	Current output set to 12mA.
ОМ	Output 20mA " Output is 20mA."
	Current output set to 20mA.
OF	Output = Rate (Input) " Output equal to input."
	Current output follows rate.
AA	Auto Data "F (DATA) R (DATA) T (DATA)"
	The response, not the echo, is sent every two seconds until it receives another message from the master. The (DATA) following the F denotes the frequency of the pulses to a precision of three places past the decimal, the (DATA) following the R denotes the rate to a precision of three places past the decimal, and the (DATA) following the T denotes the total to a precision of three places past the decimal.
DA	Dump All All of the responses in previous table.
	The HIT-2A-MIL gives all responses except for the CL command.
UI	Unit Identification "UNIT MODEL=HIT2A XX YY.ZZ"
	Model and software number for the unit. XX is the hardware revision number, YY.ZZ is the software revision where YY is the major software revision and ZZ is the minor software revision.

System Command	Description/Response/Comments
RT	Read Total "TOTAL = (DATA)" (DATA) = "0" to the following maximums: "999999.99" if TD = 3 "9999999.99" if TD = 2 "99999999.9" if TD = 1 "99999999" if TD = 0
RR	Read Rate "FLOW = (DATA)" (DATA) = "0" to the following maximums: "999999.99" if RD = 3 "9999999.99" if RD = 2 "99999999.9" if RD = 1 "99999999" if RD = 0
\mathbf{ST}^1	Set Total See ST command above.
CN	Adjust 4mA output point "CN=#(DATA)" (DATA) is the integer value that the HIT-2A-MIL sends to the 4-20mA converter to output 4mA This parameter is passed to the HIT-2A-MIL to adjust the 4mA output point of the device. This value is used in production at the test step to calibrate the 4mA output point. "CN" will cause an Invalid Command response and absence of the # symbol will cause the HIT-2A-MIL to ignore the data.

System Command	Description/Response/Comments
СМ	Adjust 20mA output point "CM=#(DATA)"
	(DATA) is the integer value that the HIT-2A-MIL sends to the 4-20mA converter to output 20mA
	This parameter is passed to the HIT-2A-MIL to adjust the 20mA output point of the device. This value is used in production at the test step to calibrate the 20mA output point. "CM" will cause an Invalid Command response and absence of the # symbol will cause the HIT-2A-MIL to ignore the data.
SA	Set Alarm Output On " Alarm Active "
	Sets the alarm output active regardless of the settings.
US	Unit Status "UNIT STAT = <data>"</data>
	Requests the status. The values for <data> with no or only one error present are: "0" - No Errors present. "128" - EPULSE error (0x080) "129" - ETOTAL error (0x081) "130" - ERATE error (0x082) "132" - EFLOW error (0x084) "129" - EERES error (0x088) (EEPROM reset to factory defaults)</data>
	If multiple errors occur, the error codes are logically OR-ed. For example, if the unit has an ETOTAL and ERATE error occurring at the same time, the <data> = "131" (0x83).</data>
CS	Clear Status " Status Cleared "
	Clears all errors.

Note:

The CL and ST commands work as follows. The ST command shall store the present value of the total in Non-Volatile memory. This total in non-volatile memory shall be the initial total in the event that device power is removed and then re-applied. The CL command will clear the total in the device and the stored total in EEPROM but retain the present total in a volatile (RAM) memory location and keep it as the old total value. Removal of power from the unit causes this old total value to be lost. When the HIT-2A-MIL receives the ST<CR> from the PC, it shall echo back the old total value until the unit adds any value to the present total. If the HIT-2A-MIL receives a second CL command, the old total value shall be set to 0.

For example, if the present total is 123.45 and the HIT-2A-MIL receives CL<CR>, the present total is cleared (set to 0.0000), the total in EEPROM is cleared, and the old total value is 123.45. If the HIT-2A-MIL receives ST<CR>, the HIT-2A-MIL echoes with the total 123.45, the old total value. If the HIT-2A-MIL receives pulses to cause the present total to increment to 0.01 and then receives a ST<CR>, the HIT-2A-MIL will echo 0.01, or the present total.

The unit mimics this behavior on the display with the Clear Total Menu and the Set total menu. The reset total input (magnet or terminal input) acts the same as the receipt of a CL<CR> from the communications link.