

*Model: CAT3-AC-MIL  
AC Powered Microprocessor  
Controlled Transmitter*

**USER'S MANUAL**



HP-325  
January 2018

***HOFFER***  
***Flow Controls***

**Perfecting Measurement™**

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## NOTICE

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This manual has been provided as an aid in installing, connecting, calibrating, operating, and servicing this unit. Every precaution for accuracy has been taken in the preparation of this manual; however, HOFFER FLOW CONTROLS, INC. neither assumes responsibility for any omissions or errors that may appear nor assumes liability for any damages that may result from the use of the products in accordance with information contained in the manual.

HOFFER FLOW CONTROLS' policy is to provide a user manual for each item supplied. Therefore, all applicable user manuals should be examined before attempting to install or otherwise connect a number of related subsystems.

During installation, care must be taken to select the correct interconnecting wiring drawing. The choice of an incorrect connection drawing may result in damage to the system and/or one of the components.

Please review the complete model number of each item to be connected and locate the appropriate manual(s) and/or drawing(s). Identify all model numbers exactly before making any connections. A number of options and accessories may be added to the main instrument, which are not shown on the basic user wiring. Consult the appropriate option or accessory user manual before connecting it to the system. In many cases, a system wiring drawing is available and may be requested from HOFFER FLOW CONTROLS.

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## Return Requests / Inquiries

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Direct all warranty and repair requests/inquiries to the Hoffer Flow Controls Customer Service Department, telephone number (252) 331-1997 or 1-800-628-4584. BEFORE RETURNING ANY PRODUCT(S) TO HOFFER FLOW CONTROLS, PURCHASER MUST OBTAIN A RETURNED MATERIAL AUTHORIZATION (RMA) NUMBER FROM HOFFER FLOW CONTROLS' CUSTOMER SERVICE DEPARTMENT (IN ORDER TO AVOID PROCESSING DELAYS). The assigned RMA number should then be marked on the outside of the return package and on any correspondence.

FOR **WARRANTY** RETURNS, please have the following information available BEFORE contacting HOFFER FLOW CONTROLS:

1. P.O. number under which the product was PURCHASED,
2. Model and serial number of the product under warranty, and
3. Repair instructions and/or specific problems relative to the product.

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1. P.O. number to cover the COST of the repair/calibration,
2. Model and serial number of the product and
3. Repair instructions and/or specific problems relative to the product.

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## LIMITED WARRANTY

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HOFFER FLOW CONTROLS, INC. ("HFC") warrants HFC's products ("goods") described in the specifications incorporated in this manual to be free from defects in material and workmanship under normal use and service, but only if such goods have been properly selected for the service intended, properly installed and properly operated and maintained. This warranty shall extend for a period of one (1) year from the date of delivery to the original purchaser (or eighteen (18) months if the delivery to the original purchaser occurred outside the continental United States). This warranty is extended only to the original purchaser ("Purchaser"). *Purchaser's sole and exclusive remedy is the repair and/or replacement of nonconforming goods as provided in the following paragraphs.*

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## **FORWARD**

The manual contains the information required to install, operate, maintain, and repair a CAT3-AC-MIL Flow Rate Signal Converter.

The CAT3-AC-MIL unit is intended to provide ship personnel with the ability to monitor the flow of fuel and other liquids.

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# 1. SAFETY

The CAT3-AC-MIL Fuel Metering unit is designed to satisfy the safety requirements for shipboard use.

The safety precautions and warnings described here are to be observed at all times. Additional precautionary messages appear throughout this manual.



## **WARNING: Risk of Electric Shock**

Remove AC power cable before opening enclosure or servicing.

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## **2. COMPLIANCE**

This instrument is designed to conform to the EMC-Directive of the Council of European Communities 89/336/EEC. This instrument has been certified to meet MIL-S-901D for shock and vibration and MIL-STD-461F for EMI compliance.

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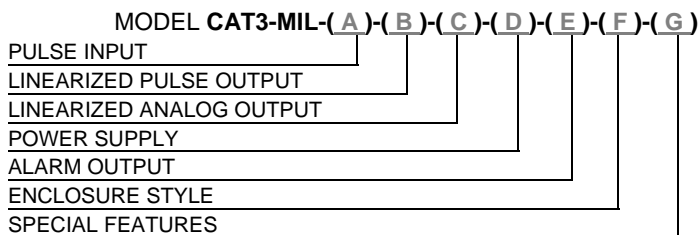
### 3. SPECIFICATIONS

Input Signal Type:	Magnetic pick up
Input frequency range:	0.2 Hz to 4 KHz
Signal level:	10 mV rms to 30 Vdc
Power supply:	120Vac, 50mA max
Analog Output:	4-20mA, 24mA overflow condition
Analog Output Response Time:	1/8 sec.*
Load resistance:	Max 650 Ohms at 24 Vdc
Accuracy:	+/- 0.02% of full scale @ 20° C
Temperature drift:	40ppm/deg C
Pulse output	0-5, 0-10V, Open Collector, AC square Internal pull-up resistor 10k Ohms Recommended load min. 50k Ohms
Maximum Pulse Frequency	1, 2, 4, 8, 100, 50% Duty Cycle
Pulse Scaling	Per flow unit of measure, divide by 1, 10, 100 100 Hz max frequency
Communications	RS232 port for Configuration and diagnostics
Operating temperature:	-40 to 85 C°
Humidity:	0-90% Non-condensing
Enclosure:	Extruded aluminum housed in Style 5 enclosure (NEMA 4)
Regulatory:	CE compliant
Linearization:	20 point

\*Limited by signal frequency and MST settings. Refer to Section 4-3.

## 6 Operation

### 3-1 Model Number Designation



#### PULSE INPUT

MODEL CAT3-MIL-(A)-( )-( )-( )-( )-( )-( )

OPTION ( A )

(1) MAG COIL, PULSE, DRY CONTACT

#### LINEARIZED PULSE OUTPUT

MODEL CAT3-MIL-( )-(B)-( )-( )-( )-( )-( )

OPTION ( B )

(4) AC SQUARE WAVE

#### LINEARIZED ANALOG OUTPUT

MODEL CAT3-MIL-( )-( )-(C)-( )-( )-( )-( )

OPTION ( C )

(1) 4-20 MA

#### POWER SUPPLY

MODEL CAT3-MIL-( )-( )-( )-(D)-( )-( )-( )

OPTION ( D )

(AC) 100-240 VAC

#### ALARM OUTPUT

MODEL CAT3-MIL-( )-( )-( )-( )-(E)-( )-( )

OPTION ( E )

(X) NONE

#### ENCLOSURE STYLE

MODEL CAT3-MIL-( )-( )-( )-( )-( )-(E)-( )

OPTIONS ( F )

(5) STYLE 5 ENCLOSURE, NEMA 4

#### SPECIAL FEATURES

MODEL CAT3-MIL-( )-( )-( )-( )-( )-( )-(G)

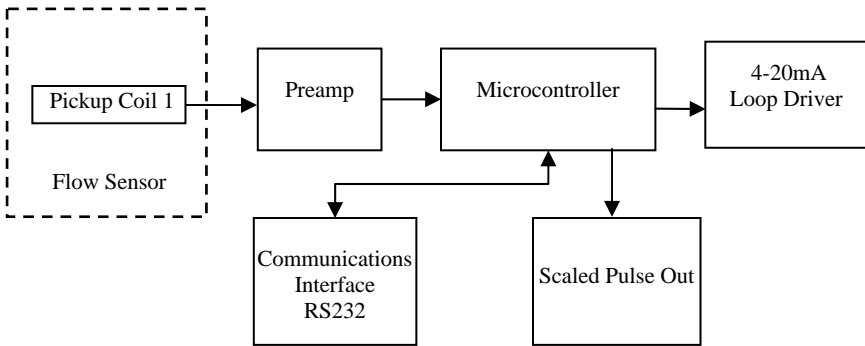
OPTIONS ( G )

(MIL) DESIGNED TO MEET EMC STDS EN5011-1992 AND EN61326-1:1997,  
MIL-S-901D FOR SHOCK AND VIBRATION AND MIL-S-462D FOR EMI  
COMPLIANCE.

## 4. OPERATION

The CAT3-AC-MIL is an AC powered microprocessor-based transmitter, which provides pulse and analog outputs. The flowmeter input circuitry will accept a magnetic type pickup, pulse and contact closure. Optional 20-point linearization is available to correct for flowmeter non-linearity, improving overall system accuracy.

### CAT3-AC-MIL Block Diagram



### 4-1 Preamplifier

The Preamplifier receives signals from the flow sensor pick up coil. The signal is amplified, filtered, and converted into a logic level square-wave before sending it to the Microcontroller.

### 4-2 Microcontroller

The Microcontroller performs all of the calculations that are required to control the analog output and pulse output. The following equations are used to calculate the flowrate and the analog output current.

## 8 Operation

$$\text{Flowrate} = \text{frequency}/\text{K-factor} \times 60$$

Where:

K-factor = Is the flow meter calibration factor in pulses/gal

Flowrate is in gal/min.

Frequency is in Hertz.

### 4-3 Analog Output

CAT3-AC-MIL provides an analog output current that is proportional to the flow rate. The analog output is scaled as follows:

$$4 \text{ mA} = 0 \text{ GPM}$$

$$20\text{mA} = \text{Max Flow Rate in GPM}$$

If the calculated flowrate is greater than the 20mA setting, the current is set to 24mA to indicate an “Over-range” condition. Microcontroller calculates the current and sends data to the Loop Driver. The Loop Driver, located on PCA183 controls the current of the loop. The Loop Driver also supplies power to the Microcontroller.

The analog output is updated 8 times per second (8 Hz). When flow stops, the time for the analog output to return to 4 mA is between 250 mS and 8 seconds, depending on the Maximum Sample Time (MST) setting. MST is a value between 1 and 80, with each count equal to 1/10<sup>th</sup> of a second. The MST setting adjusts the amount of time the electronics will wait for the next input pulse before returning to zero. This will prevent the displayed flow rate and/or analog output from going to 0 when the input frequency is less than the update time of the electronics. Adjusting the MST is only recommended for low flow applications where the minimum input frequency is below 10 Hz. The default MST setting is 1.



#### 4-4 Scaled Pulse Output

CAT3-AC-MIL Pulse Output can be configured for turbine raw frequency or for unit of measure scaled for the least significant digit of the internal total. A scaling factor of 1, 10 or 100 is available to reduce or increase the resolution of the pulse output. For example, if the Total Decimal Point is set to 0000000.0, and the Pulse Scale is 1, then 1 pulse will be output for each tenth (0.1) of a unit of measure. Changing the Pulse Scale to 10, would result in an output pulse for each 1.0 unit of measure. The output must be scaled so that the pulse frequency does not exceed the Pulse Frequency setting (100 Hz. Max) at the maximum flow rate.

#### 4-5 Communications Interface

An RS232 communications port located under the top plate allows CAT3-AC-MIL to be remotely configured and trouble-shoot using a Windows based program. Refer to the Appendix B section for communication details.

The communication function is available only when CAT3-AC-MIL device is powered.

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## 5. INSTALLATION

### 5-1 Wiring

When installing CAT3-AC-MIL, it is a good practice to use shielded cables for all input and output signals. The shield should be connected to the earth ground lug on the CAT3-AC-MIL. The shield on the opposite end of the cable should be left open.

This wiring practice is mandatory in order to comply with the requirements for Electromagnetic Compatibility, as per EMC-Directive 89/336/EEC of the Council of European Community.

### 5-2 Flowmeter Installation and Initial Startup

The performance of the turbine flowmeter is affected by the fluid swirl and non-uniform velocity profiles. It is advisable not to locate the meter run immediately downstream of pumps, partially opened valves, bends or other similar piping configurations. In addition, the area surrounding the flowmeter should be free of sources of electrical noise such as motors, solenoids, transformers and power lines which may be coupled to the pickoff device. The metering section should not be subjected to excessive vibration or shock. Such a condition may result in a mechanically induced output signal from the pickoff device.

A strainer, filter and/or air eliminator is recommended to reduce the potential of fouling or damage. On initial startup of a line, it is advisable to install a spool piece to purge the line and eliminate damage to the flowmeter due to flux, tape, solder, welds or other contaminants carried along by the fluid stream. Once completed, install the flowmeter and connect cabling to pickup coil.

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## **6. PREVENTATIVE MAINTENANCE**

### **6-1 Introduction**

Hoffer Flow Controls Flow Measurement Systems are constructed to give a long service life in the targeted measuring field and service environment. However, problems do occur from time to time and the following points should be considered for preventive maintenance and repairs.

The bearing type provided in the flowmeter is selected to provide a balance between long life, chemical resistance, ease of maintenance and performance. A preventive maintenance schedule should be established to determine the amount of wear which has occurred since last overhaul. See user's manual for flowmeter for further instructions.

Observe any scheduled organizational level maintenance instructions dictated by the requirements of the Planned Maintenance System (PMS) established by the Naval Sea System Command for fuel system components.

In the event that the flow measurement system malfunctions or becomes inoperable, refer to the Troubleshooting section of this manual.

Factory consultation is available to assist in diagnosing problems. In addition, factory repair parts and service are available for individuals who wish to utilize this service.

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## 7. TROUBLESHOOTING

### 7-1 Introduction

The troubleshooting techniques in this chapter are designed to isolate and locate the area of failure and to present the procedures for the replacement of subassemblies to make the system operational.

### 7-2 Troubleshooting Procedures

The required test equipment for troubleshooting is as follows:

Digital Multimeter: Fluke Model 8060A or equal.

Identify one of the symptoms listed below and follow the procedure. In each case proceed to the next step only if the defect is not found.

#### 7-2-1 Symptom: No flow indication when flow is present

1. Visually examine the interconnecting signal cable for broken or shorted leads.
2. With an established flowrate, configure the digital multimeter to measure AC volts, using the two volt scale. Measure voltage at the terminal, on Pin 3, SIG+ and Pin 4 SIG-. Depending on the flowrate, an approximate voltage reading of 10 millivolts to 1 volt should be measured. If voltage is present replace the electronic unit. If no voltage go to step 3.
3. Disconnect the signal cable from the electronics unit and from the flow sensor. Check the continuity of each lead of the cable. If defective replace or repair.
4. With the signal cable disconnected from the flow sensor measure the DC resistance of the pickup coil. The resistance should read between 1500 and 2200

ohms between pin A and pin B. A short or an open indicates a defective pickup coil and the pickup coil must be replaced.

5. With an established flowrate, configure the digital multimeter to measure AC volts, using the two volt scale. Connect the positive lead to pin A of pickup coil. And the negative lead to pin B of pickup coil. Depending on the flowrate an approximate voltage reading of 10 millivolts to 1 volt should be measured.
6. If zero volts are measured, a stalled rotor condition is indicated. Remove the flow sensor from the piping. Refer to flow sensor manual.

### 7-2-2 **Symptom: Flow indication with no flow present**

This symptom indicates the presence of electrical noise pickup.

1. Disconnect the signal cable from the electronics unit and from the flow sensor. Check the continuity of each lead of the cable. If defective replace or repair.
2. With the signal cable disconnected from the flow sensor measure the DC resistance of the pickup coil. The resistance should read between 1500 and 2200 ohms between pin A and pin B. A short or an open indicates a defective pickup coil and the pickup coil must be replaced.
3. Verify cable shield connection.
4. Verify electronics unit enclosure connection to ships ground.



### 7-3 Replacing the Electronics

If the electronics are determined to be faulty, follow the steps below to remove and replace the unit.

1. Turn off the power supply.
2. Open the Style 5 enclosure and unplug the 10-pin and 2-pin terminals from the headers.
3. Remove the top plate screw from the blue enclosure to disconnect ground wire.
4. Remove two mounting screws from the mounting plate on the bottom of the blue enclosure.
5. Remove the unit and install new one.
6. Replace all mounting screws and ground wire.

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## Appendix A – Default Configuration

Factory default configuration:

<i>FIELD</i>	<i>Value</i>
TAG NUMBER	10000000
LINEARIZATION	Average
K FACTOR DECIMAL POINTS	3
AVERAGE K FACTOR	1.00
NUMBER OF LINEARIZATION POINTS	20
FREQUENCY 1	4999.981
FREQUENCY 2	4999.982
FREQUENCY 3	4999.983
FREQUENCY 4	4999.984
FREQUENCY 5	4999.985
FREQUENCY 6	4999.986
FREQUENCY 7	4999.987
FREQUENCY 8	4999.988
FREQUENCY 9	4999.989
FREQUENCY 10	4999.990
FREQUENCY 11	4999.991
FREQUENCY 12	4999.992
FREQUENCY 13	4999.993
FREQUENCY 14	4999.994
FREQUENCY 15	4999.995
FREQUENCY 16	4999.996
FREQUENCY 17	4999.997
FREQUENCY 18	4999.998
FREQUENCY 19	4999.999
FREQUENCY 20	5000.000
K FACTOR 1	1.00
K FACTOR 2	1.00
K FACTOR 3	1.00
K FACTOR 4	1.00
K FACTOR 5	1.00
K FACTOR 6	1.00
K FACTOR 7	1.00
K FACTOR 8	1.00
K FACTOR 9	1.00
K FACTOR 10	1.00
K FACTOR 11	1.00
K FACTOR 12	1.00
K FACTOR 13	1.00
K FACTOR 14	1.00
K FACTOR 15	1.00

## 20 Appendix A – Default Configuration

<b><i>FIELD</i></b>	<b><i>Value</i></b>
K FACTOR 16	1.00
K FACTOR 17	1.00
K FACTOR 18	1.00
K FACTOR 19	1.00
K FACTOR 20	1.00
CORRECTION FACTOR	1.000
TOTAL UNITS	GAL
RATE UNITS	MIN
MAX SAMPLE TIME	01
4 MA SETTING	00000.000
20 MA SETTING	99.999
PULSE SCALE	OFF
PULSE OUT FREQUENCY	8
ALARM FUNCTION	OFF
ALARM SETPOINT	99999.981
CURRENT MODE	RATE
TEST PULSE	NO
ALARM TEST	NO

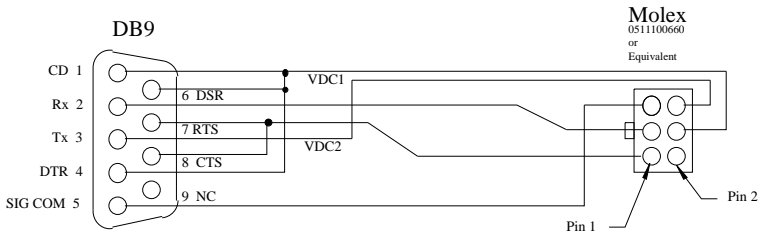
# Appendix B - Communications

## Communications Interface

CAT3-AC-MIL is equipped with a serial communication interface RS232 to allow changing flow sensor calibration parameters (k-factors). The calibration parameters must be updated whenever the flow sensor is re-calibrated. The serial port may be accessed by removing the two screws from the top plate of the blue enclosure. External power must be supplied to the CAT3 in order to communicate.

Communications with the CAT3-AC-MIL also requires the use of the HOFFER HIT2A-301 Communications Cable and the Hoffer Windows Device Configuration Software. The computer serial port must be set to the following:

Baud rate:	2400
Data bits:	8
Parity:	none
Stop bits:	1
Handshaking:	None



**HIT2A-301 Communications Cable**

# Appendix C – Drawings

